On reliability of higher order finite element method in fluid-structure interaction problems

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Outline

ntroduction

Mathematical Model

Numerical Approximation

Numerical Results

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On reliability of FEM in FSI

Sváček, P.

Outline

ntroduction

Mathematical Model

Numerical Approximation

Numerical Results

Conclusions

Outline

Introduction

Mathematical Model

- General Model
- Simplifications
- Interface Conditions

3 Numerical Approximation

- Time Discretization
- Space discretization of Fluid Model

Numerical Results

- Fluid Flow Approximation
- Fluid Approximation over Moving Structure
- Aeroelastic Simulations

5 Conclusions

On reliability of FEM in FSI

Sváček, P.

Outline

ntroduction

Mathematical Model

Numerical Approximation

Numerical Results

Conclusions

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Fluid-structure interaction problem



On reliability of FEM in FSI

Sváček, P.

Outline

Introduction

Mathematical Model

Numerical Approximation

Numerical Results

Conclusions

Air Flows Interacts with Elastic Wing Wind Tunnel in Aeronautical Test and Research Institute, Prague

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Computational Aeroelasticity

• numerical simulation of both fluid and structure motion

• fluid-structure mutual interaction

On reliability of FEM in FSI

Sváček, P.

Outline

Introduction

Mathematical Model

Numerical Approximation

Numerical Results

Conclusions

Computational Aeroelasticity

- numerical simulation of both fluid and structure motion
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 - $\bullet\,$ structure motion $\rightarrow\,$ fluid characterization
 - \bullet aerodynamical forces \rightarrow structural motion

On reliability of FEM in FSI

Sváček, P.

Outline

Introduction

Mathematical Model

Numerical Approximation

Numerical Results

Conclusions

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Goals

- determine the safe region (critical velocity)
- simulate post-critical regimes (nonlinear aeroelasticity)

On reliability of FEM in FSI

Sváček, P.

Outline

Introduction

Mathematical Model

Numerical Approximation

Numerical Results

Mathematical Model



Computational Aeroelasticity

- fluid flow model
- elastic structure
- interface conditions

On reliability of FEM in FSI

Sváček, P.

Outline

ntroduction

Mathematical Model

General Model Simplifications Interface Conditions

Numerical Approximation

Numerical Results

Conclusions

(ロ)、

Mathematical Model



Computational Aeroelasticity

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On reliability of FEM in FSI

Sváček, P.

Outline

ntroduction

Mathematical Model

General Model Simplifications Interface Conditions

Numerical Approximation

Numerical Results

Conclusions

Mathematical Model



Computational Aeroelasticity

- fluid flow model
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On reliability of FEM in FSI

Sváček, P.

Outline

ntroduction

Mathematical Model

General Model Simplifications Interface Conditions

Numerical Approximation

Numerical Results

Conclusions

Fluid Models

- incompressible viscous flow (NS eq.)
- RANS equations turbulence models

On reliability of FEM in FSI

Sváček, P.

Outline

ntroduction

Mathematical Model General Model Simplifications

Conditions

Approximation

Numerical Results

Conclusions

シック・エード・イヨ・・4日・・4日・

Navier-Stokes System of Equations

Navier-Stokes system

$$\frac{\partial \mathbf{v}}{\partial t} + (\mathbf{v} \cdot \nabla) \mathbf{v} + \nabla p - \nu \Delta \mathbf{v} = 0$$
$$\nabla \cdot \mathbf{v} = 0 \quad \text{in } \Omega_t$$

- $\bullet~ \mathbf{v}$ fluid velocity
- p pressure
- Navier-Stokes system of equations

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Sváček, P.

Outline

ntroduction

Mathematical Model General Model Simplifications Interface Conditions

Numerical Approximation

Numerical Results

Conclusions

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On reliability of FEM in FSI

Sváček, P.

Outline

ntroduction

Mathematical Model General Model Simplifications Interface

Numerical Approximation

Numerical Results

Conclusions

シック・エード・イヨ・・4日・・4日・

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Reynolds Averaging

•
$$\mathbf{v} = \mathbf{V} + \mathbf{v}'$$
, $p = P + p'$, such that $\overline{\mathbf{v}} = \mathbf{V}$

On reliability of FEM in FSI

Sváček, P.

Outline

ntroduction

Mathematical Model General Model Simplifications Interface Conditions

Numerical Approximation

Numerical Results

Conclusions

◆□▶ ◆□▶ ◆三▶ ◆三▶ 三日= のへで

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RANS equations

$$\frac{\partial V_i}{\partial t} - \nu \triangle V_i + (\mathbf{V} \cdot \nabla) V_i + \frac{\partial P}{\partial x_i} = \sum_j \frac{\partial}{\partial x_j} \left(-\overline{v'_i v'_j} \right),$$

On reliability of FEM in FSI

Sváček, P.

Outline

ntroduction

Mathematical Model General Model Simplifications Interface Conditions

Numerical Approximation

Numerical Results

Conclusions

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• Reynolds-Stresses
$$\sigma_{ij}^R = -\overline{v'_i v'_j}$$

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On reliability of FEM in FSI

Sváček, P.

Outline

ntroduction

Mathematical Model General Model Simplifications Interface Conditions

Numerical Approximation

Numerical Results

Turbulence model - SA model

Reynolds-Stresses approximation $\sigma_{ij}^{R} = -\overline{v'_{i}v'_{j}}$

Reynolds stresses are approximated

$$\sigma_{ij}^{R} = \frac{2}{3} k \delta_{ij} + \nu_{T} \left(\frac{\partial V_{i}}{\partial x_{j}} + \frac{\partial V_{j}}{\partial x_{i}} \right), \qquad \nu_{T} \approx \tilde{\nu},$$

Turbulence Modelling - Spallart-Almaras Model

$$\begin{split} \frac{\partial \tilde{\nu}}{\partial t} + (\mathbf{V} \cdot \nabla) \tilde{\nu} &= \frac{1}{\sigma} \frac{\partial}{\partial x_i} \left((\nu + \tilde{\nu}) \frac{\partial \tilde{\nu}}{\partial x_i} \right) \\ &+ \frac{c_{b_2}}{\sigma} \left(\nabla \tilde{\nu} \right)^2 + \mathcal{G} - Y, \end{split}$$

On reliability of FEM in FSI

Sváček, P.

Outline

ntroduction

Mathematical Model General Model Simplifications Interface Conditions

Numerical Approximation

Numerical Results

Conclusions

(ロ)、

Navier-Stokes system

- describes (turbulent) fluid flow
- no additional modelling is needed **BUT**

On reliability of FEM in FSI

Sváček, P.

Outline

ntroduction

Mathematical Model General Model

Simplifications Interface Conditions

Numerical Approximation

Numerical Results

Conclusions

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- time/space scales are to small to be correctly resolved in engineering computations!

On reliability of FEM in FSI

Sváček, P.

Outline

ntroduction

Mathematical Model

General Model Simplifications Interface Conditions

Numerical Approximation

Numerical Results

Conclusions

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- Reynolds Averaged Navier-Stokes system

On reliability of FEM in FSI

Sváček, P.

Outline

ntroduction

Mathematical Model General Model

Simplifications Interface Conditions

Numerical Approximation

Numerical Results

Conclusions

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• RANS desribes the mean fluid characteristics, the fluctuating part is only modelled.

On reliability of FEM in FSI

Sváček, P.

Outline

ntroduction

Mathematical Model General Model

Simplifications Interface Conditions

Numerical Approximation

Numerical Results

Conclusions

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On reliability of FEM in FSI

Sváček, P.

Outline

ntroduction

Mathematical Model General Model

Simplifications Interface Conditions

Numerical Approximation

Numerical Results

Conclusions

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- the turbulent stresses requires further modelling

On reliability of FEM in FSI

Sváček, P.

Outline

ntroduction

Mathematical Model General Model

Simplifications Interface Conditions

Numerical Approximation

Numerical Results

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- RANS desribes the mean fluid characteristics, the fluctuating part is only modelled.
- Thus: time/space scales can be correctly resolved **BUT**
- the turbulent stresses requires further modelling
- (any) turbulence model is still inexact !!!

On reliability of FEM in FSI

Sváček, P.

Outline

ntroduction

Mathematical Model General Model

Simplifications Interface Conditions

Numerical Approximation

Numerical Results

• elasticity equation

$$\rho \frac{\partial^2 u_i}{\partial t^2} - \sum_j \frac{\partial \sigma_{ij}(u)}{\partial x_j} = f_i$$

- *u* structure deflection
- special cases: linear stationary elasticity

On reliability of FEM in FSI

Sváček, P.

Outline

ntroduction

Mathematical Model General Model Simplifications

nterface Conditions

Numerical Approximation

Numerical Results

Conclusions

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On reliability of FEM in FSI

Sváček, P.

Outline

ntroduction

Mathematical Model General Model Simplifications

Interface Conditions

Numerical Approximation

Numerical Results

Conclusions

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On reliability of FEM in FSI

Sváček, P.

Outline

ntroduction

Mathematical Model General Model Simplifications

Interface Conditions

Numerical Approximation

Numerical Results

Conclusions

Flexibly Supported Airfoil



Airfoil motion equations

system ODEs

$$\begin{array}{rcl} mh + S_{\alpha}\ddot{\alpha} + K_{hh}h &=& -L \\ S_{\alpha}\ddot{h} + I_{\alpha}\ddot{\alpha} + K_{\alpha\alpha}\alpha &=& M_{3} \end{array}$$

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On reliability of FEM in FSI

Sváček, P.

Outline

ntroduction

Mathematical Model General Model Simplifications Interface Conditions

Numerical Approximation

Numerical Results

Flexibly Supported Airfoil



Airfoil motion equations

system ODEs

$$m\ddot{h} + S_{\alpha}\ddot{\alpha}\cos\alpha - S_{\alpha}\dot{\alpha}^{2}\sin\alpha + K_{hh}h = -L$$
$$S_{\alpha}\ddot{h}\cos\alpha + I_{\alpha}\ddot{\alpha} + K_{\alpha\alpha}\alpha = M_{3}$$

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On reliability of FEM in FSI

Sváček, P.

Outline

ntroduction

Mathematical Model General Model Simplifications Interface Conditions

Numerical Approximation

Numerical Results

Interface Conditions

• elastic structure model

• interface velocity w₁

$$\mathbf{v} = \mathbf{w}_I, \qquad \dot{\mathbf{u}} = \mathbf{w}_I$$

シック・エード・イヨ・・4日・・4日・

• equality of fluid/elastic forces

On reliability of FEM in FSI
Sváček, P.
Outline
Introduction
Mathematical Model
General Model Simplifications Interface Conditions
Numerical Approximation
Numerical Results
Conclusions

Interface Conditions

- elastic structure model
 - interface velocity w₁

$$\mathbf{v} = \mathbf{w}_I, \qquad \dot{\mathbf{u}} = \mathbf{w}_I$$

- equality of fluid/elastic forces
- flexibly supported airfoil model
 - airfoil surface condition

 $\mathbf{v} = \mathbf{w}_I$

シック・エード・イヨ・・4日・・4日・

 aerodynamical fluid forces L - lift and M - torsional moment

Model

- fluid flow
- flexibly supported airfoil



Sváček, P.

Outline

ntroduction

Mathematical Model General Model Simplifications Interface Conditions

Numerical Approximation

Numerical Results

Conclusions

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Model

- fluid flow
- flexibly supported airfoil

Goals

- determine the safe region (critical velocity)
- simulate post-critical regimes (nonlinear aeroelasticity)

On reliability of FEM in FSI

Sváček, P.

Outline

ntroduction

Mathematical Model General Model Simplifications Interface Conditions

Numerical Approximation

Numerical Results

Conclusions

Model

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- flexibly supported airfoil

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- how can we verify our results ?

On reliability of FEM in FSI

Sváček, P.

Outline

ntroduction

Mathematical Model General Model Simplifications Interface Conditions

Numerical Approximation

Numerical Results

Conclusions

Model

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- simulate post-critical regimes (nonlinear aeroelasticity)
- how can we verify our results ?
- compare numerical results to experimental data

On reliability of FEM in FSI

Sváček, P.

Outline

ntroduction

Mathematical Model General Model Simplifications Interface Conditions

Numerical Approximation

Numerical Results

Conclusions

Numerical Approximation

- time discretization
- space discretization
- interface conditions

On reliability of FEM in FSI

Sváček, P.

Outline

ntroduction

Mathematical Model

Numerical Approximation

Time Discretization Space discretization of Fluid Model

Numerical Results

Conclusions

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Computations on Moving Meshes

On reliability of FEM in FSI

Sváček, P.

Outline

ntroduction

Mathematical Model

Numerical Approximation

Time Discretization

opace discretization of Fluid Model

Numerical Results

Conclusions

How to approximat the time derivative ? AVI format

On reliability of FEM in FSI

Sváček, P.

Outline

ntroduction

Mathematical Model

Numerical Approximation

Time Discretization

Space discretization of Fluid Model

Numerical Results

Conclusions

Arbitrary Lagrangian-Eulerian method



Sváček, P.

Outline

ntroduction

Mathematical Model

Numerical Approximation

Time Discretization

space discretization of Fluid Model

Numerical Results

Conclusions

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Arbitrary Lagrangian-Eulerian method

• Define ALE mapping \mathcal{A}_t

$$\mathcal{A}_t: \Omega_{\mathsf{ref}} \mapsto \Omega$$

• Domain velocity (grid velocity)

$$\tilde{\mathsf{w}_g}(t,Y) = rac{\partial \mathcal{A}_t(Y)}{\partial t}$$

ALE derivative - time derivative on ALE trajectory

$$\frac{D^{\mathcal{A}}}{Dt}f = \frac{\partial f}{\partial t} + (\mathbf{w}_g \cdot \nabla)f$$

On reliability of FEM in FSI

Sváček, P.

Outline

ntroduction

Mathematical Model

Numerical Approximation

Time Discretization

Space discretization of Fluid Model

Numerical Results

Arbitrary Lagrangian-Eulerian method

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$$\mathcal{A}_t: \Omega_{\mathsf{ref}} \mapsto \Omega_t$$

• Domain velocity (grid velocity)

$$\tilde{\mathsf{w}_g}(t,Y) = rac{\partial \mathcal{A}_t(Y)}{\partial t}$$

• ALE derivative - time derivative on ALE trajectory

$$\frac{D^{\mathcal{A}}}{Dt}f = \frac{\partial f}{\partial t} + (\mathbf{w}_g \cdot \nabla)f$$

Navier-Stokes system in ALE form

$$\frac{D^{\mathcal{A}}}{Dt}\mathbf{v} + (\mathbf{v} - \mathbf{w}_g) \cdot \nabla \mathbf{v} + \nabla p - \nu \triangle \mathbf{v} = 0$$
$$\nabla \cdot \mathbf{v} = 0 \quad \text{in } \Omega_i$$

On reliability of FEM in FSI

Sváček, P.

Outline

ntroduction

Mathematical Model

Numerical Approximation

Time Discretization

discretization of Fluid Model

Numerical Results

Weak Formulation

The ALE derivative is approximated

$$\frac{D^{\mathcal{A}}\mathbf{v}}{Dt} \approx \frac{3\mathbf{v}_{n+1}-4\tilde{\mathbf{v}}_n+\tilde{\mathbf{v}}_{n-1}}{2\Delta t}$$

• Weak formulation: find $\mathbf{v}_{n+1} = \mathbf{v}$, p

Weak formulation

$$\begin{pmatrix} \frac{3\mathbf{v}}{2\Delta t}, \varphi \end{pmatrix} + \left(\left[(\mathbf{v} - \mathbf{w}_g) \cdot \nabla \right] \mathbf{v}, \varphi \right) + \nu (\nabla \mathbf{v}, \nabla \varphi)$$
$$-(p, \nabla^T \cdot \varphi) + (\nabla \cdot \mathbf{v}, q) = \left(\frac{4\tilde{\mathbf{v}}_n - \tilde{\mathbf{v}}_{n-1}}{2\Delta t}, \varphi \right)$$

On reliability of FEM in FSI

Sváček, P.

Outline

ntroduction

Mathematical Model

Numerical Approximation

Time Discretization Space discretization of Fluid Model

Numerical Results

Conclusions

FEM gives unstable results?

• very high Reynolds numbers \rightarrow convection dominated flows

$$Re_{K}^{loc} = \frac{h \|\mathbf{v}\|_{K}}{\nu} > 1$$

On reliability of FEM in FSI

Sváček, P.

Outline

ntroduction

Mathematical Model

Numerical Approximation

Time Discretization Space discretization of Fluid Model

Numerical Results

Conclusions

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• Galerkin method is unstable \rightarrow several sources of instabilities

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On reliability of FEM in FSI

Sváček, P.

Outline

ntroduction

Mathematical Model

Numerical Approximation

Time Discretization Space discretization of Fluid Model

Numerical Results

Conclusions

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FEM gives unstable results?

- Galerkin method is unstable \rightarrow several sources of instabilities
- Babuška-Brezzi (inf-sup) condition needs to be satisfied

$$\sup_{\mathbf{v}_h \in X_h} \frac{(q_h, \nabla \cdot \mathbf{v}_h)}{\|\mathbf{v}_h\|_{1,2,\Omega}} \geq c \|q_h\|_{0,2,\Omega}$$

very high Reynolds numbers → convection dominated flows

$$Re_{K}^{loc} = \frac{h \|\mathbf{v}\|_{K}}{\nu} > 1$$

On reliability of FEM in FSI

Sváček, P.

Outline

ntroduction

Mathematical Model

Numerical Approximation

Time Discretization Space discretization of Fluid Model

Numerical Results

FEM gives unstable results?

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abla\cdotoldsymbol{v}_h)}{\|oldsymbol{v}_h\|_{1,2,\Omega}}\geq c\|q_h\|_{0,2,\Omega}$$

• very high Reynolds numbers \rightarrow convection dominated flows

$$extsf{Re}_{ extsf{K}}^{ extsf{loc}} = rac{h \| \mathbf{v} \|_{ extsf{K}}}{
u} > 1$$

 \Rightarrow use Galerkin/Least-Squares stabilization

On reliability of FEM in FSI

Sváček, P.

Outline

ntroduction

Mathematical Model

Numerical Approximation

Time Discretization Space discretization of Fluid Model

Numerical Results

Conclusions

・
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Spatial discretization

• Stabilization
$$\psi = (\mathbf{w} \cdot \nabla) \varphi + \nabla q$$

$$\mathcal{L}(\boldsymbol{U},\boldsymbol{V}) = \sum_{K} \delta_{K} \left(\frac{3}{2\Delta t} \mathbf{v} - \nu \Delta \mathbf{v} + (\mathbf{w} \cdot \nabla) \mathbf{v} + \nabla p, \psi \right)_{K},$$
$$\mathcal{F}(\boldsymbol{V}) = \sum_{K} \delta_{K} \left(\frac{4\mathbf{v}^{n} - \mathbf{v}^{n-1}}{2\Delta t}, \psi \right)_{K},$$

Stabilized problem

Galerkin terms, GALS stabilization, grad-div stabilization

$$a(U, V) + \mathcal{L}(U, V) + \sum_{K \in \tau_h} \tau_K \Big(\nabla \cdot \mathbf{v}, \nabla \cdot \varphi \Big) = f(V) + \mathcal{F}(V).$$

On reliability of FEM in FSI

Sváček, P.

Outline

ntroduction

Mathematical Model

Numerical Approximation

Time Discretization Space discretization of Fluid Model

Numerical Results

Conclusions

・
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Other topics

- solution of nonlinear problem (NS) linearization
- solution of linear problem (UMFPACK)
- approximation of ODEs
- interface conditions coupling of fluid-structure models

On reliability of FEM in FSI

Sváček, P.

Outline

ntroduction

Mathematical Model

Numerical Approximation

Time Discretization Space discretization of Fluid Model

Numerical Results

Conclusions

Numerical Results

- Fluid Flow Approximation (fixed structure)
- Fluid Flow over Moving structure (validation)
- Aeroelastic Simulations

On reliability of FEM in FSI

Sváček, P.

Outline

ntroduction

Mathematical Model

Numerical Approximation

Numerical Results

Fluid Flow Approximation Fluid Approximation over Moving Structure Aeroelastic Simulations

Conclusions

Numerical Results

- Fluid Flow Approximation (fixed structure)
- Fluid Flow over Moving structure (validation)
- Aeroelastic Simulations compare to NASTRAN

On reliability of FEM in FSI

Sváček, P.

Outline

ntroduction

Mathematical Model

Numerical Approximation

Numerical Results

Fluid Flow Approximation Fluid Approximation over Moving Structure Aeroelastic Simulations

Conclusions

Boundary layer approximation



On reliability of FEM in FSI

Approximation of Boundary Layer - Taylor Hood

- laminar flow $(Re = 2 \cdot 10^5)$
- FE Dimension: 16683 x 2 + 4242 = 37608
- Nodes: 4242
- Elements: 8200



On reliability of FEM in FSI

Sváček, P.

Outline

ntroduction

Mathematical Model

Numerical Approximation

Numerical Results

Fluid Flow Approximation Fluid Approximation over Moving Structure Aeroelastic Simulations

Conclusions

Blasius solution - Taylor-Hood

- laminar flow $(Re = 2 \cdot 10^5)$
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On reliability of FEM in FSI

Sváček, P.

Outline

ntroduction

Mathematical Model

Numerical Approximation

Numerical Results

Fluid Flow Approximation Fluid Approximation over Moving Structure Aeroelastic Simulations

Conclusions

◆□▶ ◆□▶ ◆ 三▶ ◆ 三▶ 三国本 のへで

Blasius solution - Taylor-Hood

- laminar flow $(Re = 2 \cdot 10^5)$
- FE Dimension: 16683 x 2 + 4242 = 37608
- Nodes: 4242 Elements: 8200
- Can we improve that?



On reliability of FEM in FSI

Sváček, P.

Outline

ntroduction

Mathematical Model

Numerical Approximation

Numerical Results

Fluid Flow Approximation Fluid Approximation over Moving Structure Aeroelastic Simulations

Conclusions

◆□▶ ◆□▶ ◆ 三▶ ◆ 三▶ 三日= のへで

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On reliability of FEM in FSI

Sváček, P.

Outline

ntroduction

Mathematical Model

Numerical Approximation

Numerical Results

Fluid Flow Approximation Fluid Approximation over Moving Structure Aeroelastic Simulations

Conclusions

Blasius solution - P3/P2 elements

- laminar flow $(Re = 2 \cdot 10^5)$
- uniform p-distribution
- FE Dimension: 4012 x 2 + 1809 = 9833
- Nodes: 472
- Elements: 866



On reliability of FEM in FSI

Sváček, P.

Outline

ntroduction

Mathematical Model

Numerical Approximation

Numerical Results

Fluid Flow Approximation Fluid Approximation over Moving Structure Aeroelastic Simulations

Conclusions

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Blasius solution - P4/P3 elements

- laminar flow $(Re = 2 \cdot 10^5)$
- FE Dimension: 2x13235 (Velocity) + 7483 (Pressure) = 33953
- Nodes: 866, Elements: 1629



On reliability of FEM in FSI

Sváček, P.

Outline

ntroduction

Mathematical Model

Numerical Approximation

Numerical Results

Fluid Flow Approximation Fluid Approximation over Moving Structure Aeroelastic Simulations

Conclusions

◆□▶ ◆□▶ ◆ 三▶ ◆ 三▶ 三日= のへで

On reliability of FEM in FSI

Sváček, P.

Outline

ntroduction

Mathematical Model

Numerical Approximation

Numerical Results

Fluid Flow Approximation Fluid Approximation over Moving Structure Aeroelastic Simulations

Conclusions

Fluid velocity isolines, $Re = 5 \cdot 10^5$, AVI format

◆□▶ ◆□▶ ◆三▶ ◆三▶ 三三 のへ⊙

On reliability of FEM in FSI

Sváček, P.

Outline

ntroduction

Mathematical Model

Numerical Approximation

Numerical Results

Fluid Flow Approximation Fluid Approximation over Moving Structure Aeroelastic Simulations

Conclusions

Fluid velocity isolines, $Re = 5 \cdot 10^5$ AVI format

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- aerodynamical lift coefficient (time averaged values)
- comparison with experimental data for NACA $63_2 415$



On reliability of FEM in FSI

Sváček, P.

Outline

ntroduction

Mathematical Model

Numerical Approximation

Numerical Results

Fluid Flow Approximation Fluid Approximation over Moving Structure Aeroelastic Simulations

- aerodynamical moment coefficient (time averaged values)
- \bullet comparison with experimental data for NACA 63₂ 415



◆□▶ ◆□▶ ◆三▶ ◆三▶ 三国王 のへ⊙

On reliability of FEM in FSI

Sváček, P.

Outline

Introduction

Mathematical Model

Numerical Approximation

Numerical Results

Fluid Flow Approximation Fluid Approximation over Moving Structure Aeroelastic Simulations

- aerodynamical lift coefficient (time averaged values)
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Outline

Fluid Flow Approximation

On reliability Prescribed vibrations of α , 30 Hz, amplitude 3,2,1 degrees.



of FEM in FSI

Model

Fluid Approximation over Moving Structure

Prescribed vibrations of α , 30 Hz, amplitude 1 degree.



Pressure coeficient (up/down) at x/c = 0.15 - dependence on time.

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Sváček, P.

Outline

ntroduction

Mathematical Model

Numerical Approximation

Numerical Results Fluid Flow Approximation Fluid Approximation over Moving Structure Aeroelastic Simulations

Pressure Coefficient

• What is pressure coefficient?

$$c_p = \frac{p - p_0}{\frac{1}{2}\rho U_\infty^2}$$

for prescribed vibrations

$$\alpha = \alpha_0 \cdot \sin(2\pi ft)$$

the pressure at airfoil surface is expected to behave like

$$c_p = c_p^{\text{mean}} + c_p' \sin(2\pi ft) + c_p'' \cos(2\pi ft)$$

 comparison with experimental data Benetka, J. et al, Tech. report 3418/02, ARTI, 2002, Triebstein, H., 1986., J. Aircraft 23.

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On reliability of FEM in FSI

Sváček, P.

Outline

ntroduction

Mathematical Model

Numerical Approximation

Numerical Results Fluid Flow Approximation Fluid Approximation over Moving Structure Aeroelastic Simulations

Comparison of c_p^{mean} with experimental data



On reliability of FEM in FSI

Sváček, P.

Outline

ntroduction

Mathematical Model

Numerical Approximation

Numerical Results

Approximation Fluid Approximation over Moving Structure

Aeroelastic Simulations

Comparison of c'_p with experimental data



Comparison of c'_p with experimental data

On reliability of FEM in FSI

Sváček, P.

Outline

ntroduction

Mathematical Model

Numerical Approximation

Numerical Results

Fluid Flow Approximation Fluid Approximation over Moving Structure

Simulations

Comparison of c''_p with experimental data



On reliability of FEM in FSI

Stall Flutter Approximation

$$\alpha = (10 + 10 \cdot \sin(2\pi ft)), Re = 5000$$

Naudasher, E., Rockwell, D., Flow-Induced Vibrations, 1994

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Sváček, P.

Outline

ntroduction

Mathematical Model

Numerical Approximation

Numerical Results Fluid Flow Approximation over Moving Structure Aeroelastic Simulations

Conclusions

Stall Flutter Approximation

 $\alpha = (10 + 10 \cdot \sin(2\pi ft)), Re = 5000$



 $\alpha = 19.4553$ $\alpha = 12.045$ $\alpha = 8.06$ Naudasher, E., Rockwell, D., *Flow-Induced Vibrations*, 1994

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Sváček, P.

Outline

ntroduction

Mathematical Model

Numerical Approximation

Numerical Results Fluid Flow Approximation Fluid Approximation over Moving Structure Aeroelastic Simulations

Conclusions

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Stall Flutter

On reliability of FEM in FSI

Sváček, P.

Outline

ntroduction

Mathematical Model

Numerical Approximation

Numerical Results

Fluid Flow Approximation Fluid Approximation over Moving Structure Aeroelastic

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Conclusions

Fluid velocity isolines, $Re = 5 \cdot 10^5$ AVI(1) format

Aeroelastic simulations - laminar



 $\underbrace{E}_{40}^{0} \underbrace{1}_{20}^{0} \underbrace{1}_{00}^{0} \underbrace{1}_{0}^{0} \underbrace{1}_{00}^{0} \underbrace$

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 $U_{\infty}=4~{
m m/s}$

On reliability of FEM in FSI

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Outline

ntroduction

Mathematical Model

Numerical Approximation

Numerical Results

Fluid Flow Approximation Fluid Approximation over Moving Structure Aeroelastic

Simulations




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On reliability of FEM in FSI

Sváček, P.

Outline

ntroduction

Mathematical Model

Numerical Approximation

Numerical Results

Fluid Flow Approximation Fluid Approximation over Moving Structure Aeroelastic

Simulations

Conclusions



On reliability of FEM in FSI

Sváček, P.

Outline

ntroduction

Mathematical Model

Numerical Approximation

Numerical Results

Fluid Flow Approximation Fluid Approximation over Moving Structure Aeroelastic

Simulations

Conclusions



On reliability of FEM in FSI

Sváček, P.

Outline

ntroduction

Mathematical Model

Numerical Approximation

Numerical Results

Fluid Flow Approximation Fluid Approximation over Moving Structure Aeroelastic

Simulations

Conclusions



On reliability of FEM in FSI

Sváček, P.

Outline

ntroduction

Mathematical Model

Numerical Approximation

Numerical Results

Fluid Flow Approximation Fluid Approximation over Moving Structure Aeroelastic

Simulations

Conclusions



On reliability of FEM in FSI

Sváček, P.

Outline

ntroduction

Mathematical Model

Numerical Approximation

Numerical Results

Fluid Flow Approximation Fluid Approximation over Moving Structure Aeroelastic

Simulations

Conclusions



On reliability of FEM in FSI

Sváček, P.

Outline

ntroduction

Mathematical Model

Numerical Approximation

Numerical Results

Fluid Flow Approximation Fluid Approximation over Moving Structure Aeroelastic

Simulations

Conclusions



On reliability of FEM in FSI

Sváček, P.

Outline

ntroduction

Mathematical Model

Numerical Approximation

Numerical Results

Fluid Flow Approximation Fluid Approximation over Moving Structure Aeroelastic

Simulations

Conclusions



On reliability of FEM in FSI

Sváček, P.

Outline

ntroduction

Mathematical Model

Numerical Approximation

Numerical Results

Fluid Flow Approximation Fluid Approximation over Moving Structure Aeroelastic

Simulations

Conclusions



On reliability of FEM in FSI

Sváček, P.

Outline

ntroduction

Mathematical Model

Numerical Approximation

Numerical Results

Fluid Flow Approximation Fluid Approximation over Moving Structure Aeroelastic Simulations

_

Conclusions



On reliability of FEM in FSI

Sváček, P.

Outline

ntroduction

Mathematical Model

Numerical Approximation

Numerical Results

Fluid Flow Approximation Fluid Approximation over Moving Structure Aeroelastic

Simulations

Conclusions

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On reliability of FEM in FSI

Sváček, P.

Outline

ntroduction

Mathematical Model

Numerical Approximation

Numerical Results

Fluid Flow Approximation Fluid Approximation over Moving Structure Aeroelastic Simulations

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Conclusions

 $U_{\infty} = 40 \text{ m/s}$

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On reliability of FEM in FSI

Sváček, P.

Outline

ntroduction

Mathematical Model

Numerical Approximation

Numerical Results

Fluid Flow Approximation Fluid Approximation over Moving Structure Aeroelastic

Simulations

Conclusions

- flexibly supported airfoil NACA 0012
- RANS + Spallart-Almaras turbulence model
- NASTRAN computation with the STRIP model critical speed $U_{\infty}=37.7m/s$
- frequencies and damping comparison

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Sváček, P.

Outline

ntroduction

Mathematical Model

Numerical Approximation

Numerical Results Fluid Flow Approximation Fluid Approximation over Moving Structure Aeroelastic Simulations

Conclusions



Solution of the coupled aeroelastic model (h,α), U = 5m/s

On reliability of FEM in FSI

Sváček, P.

Outline

ntroduction

Mathematical Model

Numerical Approximation

Numerical Results Fluid Flow Approximation Fluid Approximation over Moving Structure Aeroelastic Simulations

Conclusions



Solution of the coupled aeroelastic model (h,α), U = 7.5m/s

On reliability of FEM in FSI

Sváček, P.

Outline

ntroduction

Mathematical Model

Numerical Approximation

Numerical Results Fluid Flow Approximation Fluid Approximation over Moving Structure Aeroelastic Simulations

Conclusions



Solution of the coupled aeroelastic model (h,α), U = 10m/s

On reliability of FEM in FSI

Sváček, P.

Outline

ntroduction

Mathematical Model

Numerical Approximation

Numerical Results Fluid Flow Approximation Fluid Approximation over Moving Structure Aeroelastic Simulations

Conclusions



Solution of the coupled aeroelastic model (h,α), U = 12.5m/s

On reliability of FEM in FSI

Sváček, P.

Outline

ntroduction

Mathematical Model

Numerical Approximation

Numerical Results Fluid Flow Approximation Fluid Approximation over Moving Structure Aeroelastic Simulations

Conclusions



Solution of the coupled aeroelastic model (h,α), U = 15m/s

On reliability of FEM in FSI

Sváček, P.

Outline

ntroduction

Mathematical Model

Numerical Approximation

Numerical Results Fluid Flow Approximation Fluid Approximation over Moving Structure Aeroelastic Simulations

Conclusions



Solution of the coupled aeroelastic model (h,α), U = 17.5m/s

On reliability of FEM in FSI

Sváček, P.

Outline

ntroduction

Mathematical Model

Numerical Approximation

Numerical Results Fluid Flow Approximation Fluid Approximation over Moving Structure Aeroelastic Simulations

Conclusions



Solution of the coupled aeroelastic model (h,α), U = 20m/s

On reliability of FEM in FSI

Sváček, P.

Outline

ntroduction

Mathematical Model

Numerical Approximation

Numerical Results Fluid Flow Approximation Fluid Approximation over Moving Structure Aeroelastic Simulations

Conclusions



Solution of the coupled aeroelastic model (h,α), U = 22.5m/s

On reliability of FEM in FSI

Sváček, P.

Outline

ntroduction

Mathematical Model

Numerical Approximation

Numerical Results Fluid Flow Approximation Fluid Approximation over Moving Structure Aeroelastic Simulations

Conclusions



Solution of the coupled aeroelastic model (h,α), U = 25m/s

On reliability of FEM in FSI

Sváček, P.

Outline

ntroduction

Mathematical Model

Numerical Approximation

Numerical Results Fluid Flow Approximation Fluid Approximation over Moving Structure Aeroelastic Simulations

Conclusions



Solution of the coupled aeroelastic model (h,α), U = 27.5m/s

On reliability of FEM in FSI

Sváček, P.

Outline

ntroduction

Mathematical Model

Numerical Approximation

Numerical Results Fluid Flow Approximation Fluid Approximation over Moving Structure Aeroelastic Simulations

Conclusions



Solution of the coupled aeroelastic model (h,α), U = 30m/s

On reliability of FEM in FSI

Sváček, P.

Outline

ntroduction

Mathematical Model

Numerical Approximation

Numerical Results Fluid Flow Approximation Fluid Approximation over Moving Structure Aeroelastic Simulations

Conclusions



Solution of the coupled aeroelastic model (h,α), U = 32.5m/s

On reliability of FEM in FSI

Sváček, P.

Outline

ntroduction

Mathematical Model

Numerical Approximation

Numerical Results Fluid Flow Approximation Fluid Approximation over Moving Structure Aeroelastic Simulations

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Solution of the coupled aeroelastic model (h,α), U = 35m/s

On reliability of FEM in FSI

Sváček, P.

Outline

ntroduction

Mathematical Model

Numerical Approximation

Numerical Results Fluid Flow Approximation Fluid Approximation over Moving Structure Aeroelastic Simulations

Conclusions



Solution of the coupled aeroelastic model (h,α), U = 36m/s

On reliability of FEM in FSI

Sváček, P.

Outline

ntroduction

Mathematical Model

Numerical Approximation

Numerical Results Fluid Flow Approximation Fluid Approximation over Moving Structure Aeroelastic Simulations

Conclusions



Solution of the coupled aeroelastic model (h,α), U = 37m/s

On reliability of FEM in FSI

Sváček, P.

Outline

ntroduction

Mathematical Model

Numerical Approximation

Numerical Results Fluid Flow Approximation Fluid Approximation over Moving Structure Aeroelastic Simulations

Conclusions

- U=37 m/s
- velocity isolines, AVI format

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Sváček, P.

Outline

ntroduction

Mathematical Model

Numerical Approximation

Numerical Results

Fluid Flow Approximation Fluid Approximation over Moving Structure Aeroelastic

Simulations

Conclusions

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Comparison with NASTRAN computation



Frequencies comparison

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On reliability of FEM in FSI

Sváček, P.

Outline

ntroduction

Mathematical Model

Numerical Approximation

Numerical Results Fluid Flow

Fluid Approximation over Moving Structure

Aeroelastic Simulations

Conclusions

Comparison with NASTRAN computation



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Summary

- NS solver numerical results were compared to experimental/computational data.
- NS solver and RANS solver results for aeroelastic problem were compared each to other.
- Performence: RANS × NS (?)

Conclusion

RANS and NS shows good agreement with NASTRAN computations.

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Outline

ntroduction

Mathematical Model

Numerical Approximation

Numerical Results

Conclusions

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Summary

- NS solver numerical results were compared to experimental/computational data.
- NS solver and RANS solver results for aeroelastic problem were compared each to other.
- Performence: RANS × NS (?)

Conclusion

- RANS and NS shows good agreement with NASTRAN computations.
- We must provide: careful mesh design, time step value, ...

On reliability of FEM in FSI

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Outline

ntroduction

Mathematical Model

Numerical Approximation

Numerical Results

Conclusions

Summary

- NS solver numerical results were compared to experimental/computational data.
- NS solver and RANS solver results for aeroelastic problem were compared each to other.
- Performence: RANS × NS (?)

Conclusion

- RANS and NS shows good agreement with NASTRAN computations.
- How to increase reliability?

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Outline

ntroduction

Mathematical Model

Numerical Approximation

Numerical Results

Conclusions

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Can the grid motion "pollute" the solution?

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Can the grid motion "pollute" the solution?

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AVI format Test Problem: constant fluid velocity $\mathbf{v} = (1, 0)$ on rectangle.
Use anallytical derivative of ALE mapping ...

 $\mathbf{w}_{g} = \frac{\partial \mathbf{x}}{\partial t}$

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Use finite difference formula ...

$$\mathbf{w}_g \approx \frac{\mathbf{3}x^{(n+1)} - \mathbf{x}^{(n)} + \mathbf{x}^{(n-1)}}{2\Delta t}$$

Crid Motion Influence on Solution (finite difference

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The ALE derivative approximation

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- use \mathbf{v}_{n-1} defined on Ω_{n-1}
- \mathbf{v}_n defined on Ω_n

The ALE derivative approximation

- use \mathbf{v}_{n-1} defined on Ω_{n-1}
- \mathbf{v}_n defined on Ω_n
- and \mathbf{v}_{n+1} defined on Ω_{n+1}

$$rac{D^{\mathcal{A}}\mathbf{v}}{Dt} ~~pprox ~~rac{3\mathbf{v}_{n+1}-4\mathbf{ ilde{v}}_n+\mathbf{ ilde{v}}_{n-1}}{2\Delta t}$$

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The ALE derivative approximation

- use \mathbf{v}_{n-1} defined on Ω_{n-1}
- \mathbf{v}_n defined on Ω_n

• where $\tilde{\mathbf{v}}_n$ and $\tilde{\mathbf{v}}_{n-1}$ lives on Ω_{n+1}

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Spatial discretization

• Stabilization
$$\psi = (\mathbf{w} \cdot \nabla) \varphi + \nabla q$$

$$\begin{split} \mathcal{L}(\boldsymbol{U},\boldsymbol{V}) &= \sum_{\mathcal{K}} \delta_{\mathcal{K}} \left(\frac{3}{2\tau} \mathbf{v} - \nu \triangle \mathbf{v} + (\mathbf{w} \cdot \nabla) \, \mathbf{v} + \nabla p, \psi \right)_{\mathcal{K}}, \\ \mathcal{F}(\boldsymbol{V}) &= \sum_{\mathcal{K}} \delta_{\mathcal{K}} \left(\frac{4 \mathbf{v}^{n} - \mathbf{v}^{n-1}}{2\tau}, \psi \right)_{\mathcal{K}}, \end{split}$$

Stabilized problem

- Gelhard, T., Lube, G., Olshanskii, M. A., 2004. Stabilized finite element schemes with BB-stable elements for incompressible flows. *Journal of Computational and Applied Mathematics* (accepted).
- Gelhard, T., Lube, G., Olshanskii, M. A., 2004. Stabilized finite element schemes with LBB-stable elements for incompressible flows. *Journal of Computational and Applied Mathematics*.

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